

Keynesian Models for Analysis of Macroeconomic Policy

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Vast literature in macroeconomic modelling

- Keynes (1936), Hicks (1937), Samuelson (1939),
- Phillips (1958), Friedman (1968), Phelps (1968), Tobin (1969),
- Sargent and Wallace (1975), Lucas (1976), Fisher (1977), Kydland and Prescott (1977), Wallis (1980), King and Plosser (1984) Mankiw (1989), Prescott (1986), Taylor (1987)
- Blanchard and Kiyotaki (1987), Manning (1995), Rankin (1992)
- Barro and Gordon (1983), Sargent (1986) Goodhart (1989), Nickell (1990), Mankiw and Romer (1993), Lockwood Miller and Zhang (1998)
- Wallis (1989), MPC (1999), Pagan and Wickens (1989), Hendry (1995), Holly Weale (2000)
- Taylor (1993), Sargent and Ljungqvists (2000), Minford and Peel (2002), Blake and Weal (2003), Garratt, Lee, Pesaran and Shin (2003)
- Solow (1956), Lucas (1988), Romer (1990), Mankiw, Romer and Weil (1992),
- Harrod (1939), Domar (1947) and Solow (1956), Parente and Prescott (1993)
- Fullerton, Shoven and Whalley (1983), Auerbach and Kotlikoff (1987), Perroni (1995), Rutherford (1995), Bank of England, NIESR) ₂ Kehoe, Srinivasan and Whalley (2005), Bhattarai (1997, 1999)

Multiplier-accelerator model of Samuelson (1939)

$$Y_t = C_t + I_t + G_0$$

$$C_t = \gamma Y_{t-1} \quad 0 < \gamma < 1$$

$$I_t = \alpha(\gamma C_t - \gamma C_{t-1}) \quad \alpha > 0$$

$$Y_t = \gamma(1 + \alpha)Y_{t-1} - \alpha\gamma Y_{t-2} + G_0$$

$$\bar{Y} = \frac{G_0}{1 - \gamma(1 + \alpha) + \alpha\gamma} = \frac{G_0}{1 - \gamma}$$

Transitional Dynamics

$$Y_t - \gamma(1 + \alpha)Y_{t-1} + \alpha\gamma Y_{t-2} = 0$$

$$Ab^t - \gamma(1 + \alpha)Ab^{t-1} + \alpha\gamma Ab^{t-2} = 0$$

$$b_1, b_2 = \frac{\gamma(1 + \alpha) \pm \sqrt{\gamma^2(1 + \alpha)^2 - 4\alpha\gamma}}{2}$$

$$Y_t = A_1 b_1^t + A_2 b_2^t$$

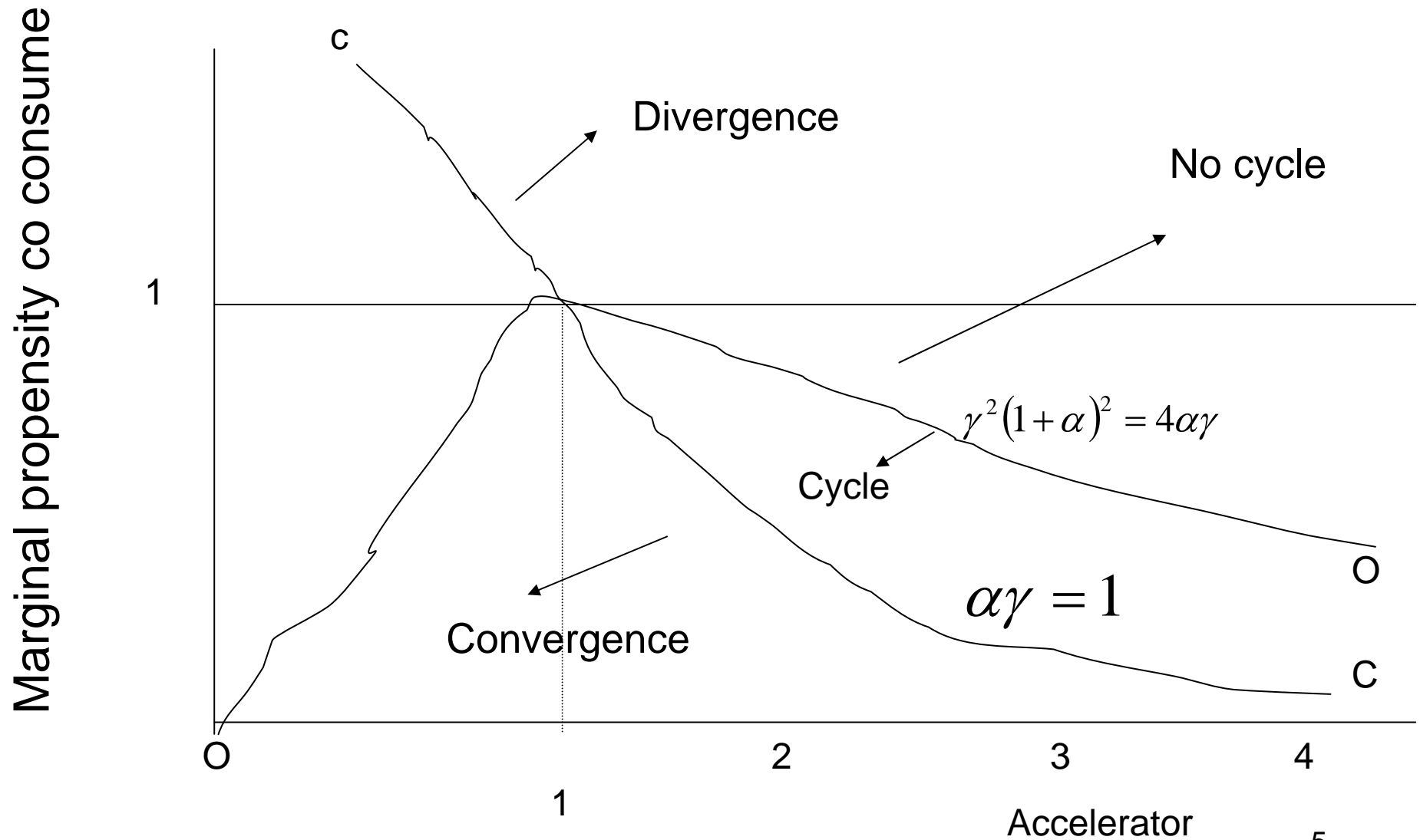
Three cases:

$$\gamma^2(1 + \alpha)^2 > 4\alpha\gamma$$

$$\gamma^2(1 + \alpha)^2 = 4\alpha\gamma$$

$$\gamma^2(1 + \alpha)^2 < 4\alpha\gamma$$

Convergence or divergence , cycle or no cycle



$$Y_t = A_1 R^t (\cos \theta \cdot t + i \sin \theta \cdot t) + A_2 R^t (\cos \theta \cdot t - i \sin \theta \cdot t)$$

Application of the Multiplier Accelerator Model

$$C_t = \beta_0 + \beta_1(Y_t - T_t)$$

$$I_t = \mu_0 + \mu_1 R_t + \phi \Delta Y_{t-1}$$

$$T_t = t_0 + t_1 Y_t$$

$$M_t = m_0 + m_1 Y_t + m_2 \lambda_t$$

$$C_t + T_t + S_t = Y_t = C_t + I_t + G_t + X_t - M_t$$

$$(T_t - G_t) + (S_t - I_t) = (X_t - M_t)$$

$$Y_t = \frac{\beta_0 - \beta_1 c_0 + \mu_0 - m_0 + G_t + X_t}{1 - \beta_1 + \beta_1 t_1 + m_1} + \frac{\mu_1 R_t}{1 - \beta_1 + \beta_1 t_1 + m_1} + \frac{\phi \Delta Y_{t-1}}{1 - \beta_1 + \beta_1 t_1 + m_1}$$

Parametric Specification of the Keynesian Model

	Parameter s	Base Case	Tax cut	Spending	MPC	T &G	High X	High I	MMM
G	200	200	200	400	200	400	200	200	200
X	100	100	100	100	100	100	300	100	100
r	0.1	0.1	0.1	0.1	0.1	0.1	0.1	0.1	0.1
C0	300	300	300	300	300	300	300	300	300
b	0.8	0.8	0.8	0.8	0.9	0.8	0.8	0.8	0.8
I0	50	50	50	50	50	50	50	200	50
d	10	10	10	10	10	10	10	10	10
t0	30	30	30	30	30	30	30	30	30
t	0.3	0.3	0.2	0.2	0.3	0.2	0.3	0.3	0.3
m0	20	20	20	20	20	20	20	20	20
m1	0.25	0.25	0.25	0.25	0.25	0.25	0.25	0.25	0.4

Solutions of the Basic Keynesian Model

	Y	T	C	I	G	X	M	S	T-G	X-M	S-I	Bal
Base case	876.8	293.0	767.0	49.0	200.0	100.0	239.2	183.2	93.0	139.2	232.2	139.2
Tax cut	991.8	228.4	910.8	49.0	200.0	100.0	268.0	147.3	28.4	168.0	196.3	168.0
Spending	1166.7	380.0	929.3	49.0	400.0	100.0	311.7	142.7	-20.0	211.7	191.7	211.7
MPC	971.0	321.3	884.7	49.0	200.0	100.0	262.7	235.0	121.3	162.7	284.0	162.7
T&G	1319.7	293.9	1120.6	49.0	400.0	100.0	349.9	-94.9	106.1	249.9	143.9	249.9
High X	1166.7	380.0	929.3	49.0	200.0	300.0	311.7	142.7	180.0	-11.7	191.7	-11.7
High I	1094.2	358.3	888.8	199.0	200.0	100.0	293.6	152.8	158.3	193.6	351.8	193.6
MMM	720.2	246.1	679.3	49.0	200.0	100.0	308.1	205.2	46.1	208.1	254.2	208.1

Keynesian IS-LM Model

$$\left(\frac{\overline{MM}}{P}\right)_t = b_0 + b_1 Y_t - b_2 R_t$$

$$R_t = \frac{b_0}{b_2} - \frac{1}{b_2} \left(\frac{\overline{MM}}{P}\right)_t + \frac{b_1}{b_2} Y_t$$

$$Y_t = \frac{b_2 \left(\begin{matrix} \beta_0 - \beta_1 t + \mu_0 - m_0 + G_t + X_t \\ 1 - \beta_1 + \beta_1 t + m_1 \end{matrix} \right) b_2 - \mu_1 b_2}{\left(\begin{matrix} \beta_0 - \beta_1 t + \mu_0 - m_0 + G_t + X_t \\ 1 - \beta_1 + \beta_1 t + m_1 \end{matrix} \right) b_2 - \mu_1 b_2} + \frac{b_2 \phi \Delta Y_{t-1}}{\left(\begin{matrix} \beta_0 - \beta_1 t + \mu_0 - m_0 + G_t + X_t \\ 1 - \beta_1 + \beta_1 t + m_1 \end{matrix} \right) b_2 - \mu_1 b_2} + \frac{b_2 \mu_1}{\left(\begin{matrix} \beta_0 - \beta_1 t + \mu_0 - m_0 + G_t + X_t \\ 1 - \beta_1 + \beta_1 t + m_1 \end{matrix} \right) b_2 - \mu_1 b_2} \left[\frac{b_0}{b_2} - \frac{1}{b_2} \left(\frac{\overline{MM}}{P}\right)_t \right]$$

$$R_t = \frac{b_0}{b_2} - \frac{1}{b_2} \left(\frac{\overline{MM}}{P}\right)_t + \frac{b_1}{b_2} \left[\frac{b_2 \left(\begin{matrix} \beta_0 - \beta_1 t + \mu_0 - m_0 + G_t + X_t \\ 1 - \beta_1 + \beta_1 t + m_1 \end{matrix} \right) b_2 - \mu_1 b_2}{\left(\begin{matrix} \beta_0 - \beta_1 t + \mu_0 - m_0 + G_t + X_t \\ 1 - \beta_1 + \beta_1 t + m_1 \end{matrix} \right) b_2 - \mu_1 b_2} + \frac{b_2 \phi \Delta Y_{t-1}}{\left(\begin{matrix} \beta_0 - \beta_1 t + \mu_0 - m_0 + G_t + X_t \\ 1 - \beta_1 + \beta_1 t + m_1 \end{matrix} \right) b_2 - \mu_1 b_2} + \frac{b_2 \mu_1}{\left(\begin{matrix} \beta_0 - \beta_1 t + \mu_0 - m_0 + G_t + X_t \\ 1 - \beta_1 + \beta_1 t + m_1 \end{matrix} \right) b_2 - \mu_1 b_2} \left[\frac{b_0}{b_2} - \frac{1}{b_2} \left(\frac{\overline{MM}}{P}\right)_t \right] \right]$$

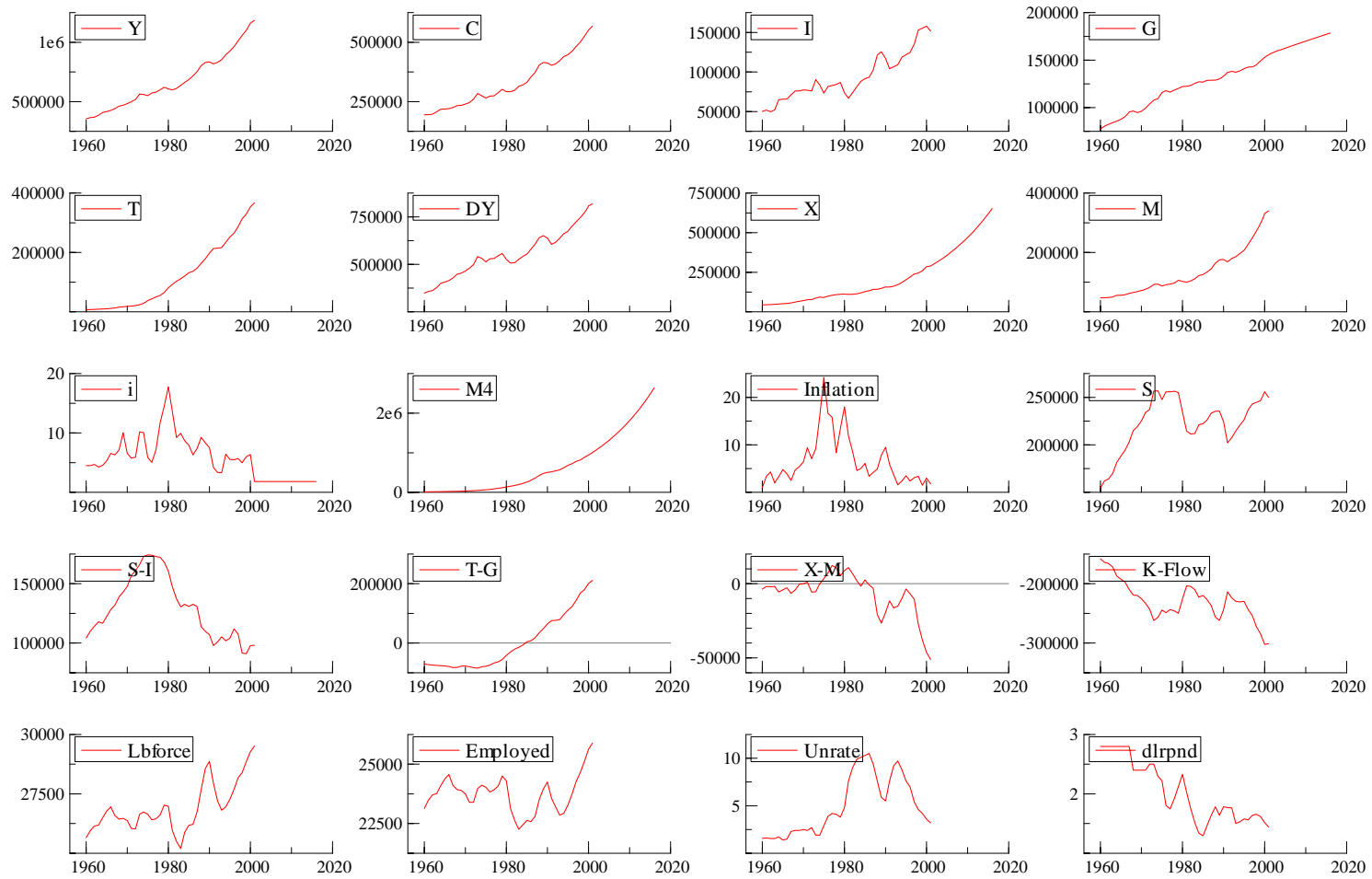
Parameters of the IS-LM Model

beta0	10000	10000	10000	10000	10000	10000	10000	10000	10000	10000	22114.16	
beta1	0.9	0.9	0.9	0.9	0.9	0.9	0.9	0.9	0.6	0.9	0.459078	
mu0	500	500	500	500	500	500	1000	500	500	500	105457	
m0	100	100	100	100	100	100	100	100	100	100	-65167	
t0	200	500	200	500	200	200	200	200	200	200	-201384	
t1	0.3	0.3	0.3	0.3	0.3	0.3	0.3	0.3	0.3	0.3	0.476403	
m1	0.2	0.2	0.2	0.2	0.2	0.2	0.2	0.2	0.2	0.2	1.387408	
mu1	1000	1000	1000	1000	1000	1000	1000	1000	1000	1000	1720.051	
phi	0.6	0.6	0.6	0.6	0.6	0.6	0.6	0.6	0.6	0.6	0.6	
G	20000	20000	25000	25000	20000	20000	20000	20000	20000	20000	155880	
X	8000	8000	8000	8000	8000	8000	8000	10000	10000	8000	289225	
y0	500	500	500	500	500	500	500	500	500	500	500	
b0	800	800	800	800	800	800	800	800	800	800	-78809	
b1	0.25	0.25	0.25	0.25	0.25	0.25	0.25	0.25	0.25	0.25	0.333992	
b2	300000	300000	300000	300000 0	300000	600000	300000	300000	300000	300000	300000	-1829.75
M4	10000	10000	10000	10000	15000	10000	10000	10000	10000	10000	10000	
P	1	1	1	1	1	1	1	1	1	1	1	

Solution of the IS-LM Model

	R	Y	C	I	G	T	M	X	S	X-M	S-I	T-G
Base case	0.0 251	669 01	519 68	525	200 00	202 70	134 80	800 0	- 5337	-5480	-5862	270
More Tax	0.0 24	656 40	504 53	524	200 00	206 92	132 28	800 0	- 5505	-5228	-6029	692
More Spending	0.0 324	756 60	574 86	532	250 00	228 98	152 32	800 0	- 4724	-7232	-5256	-2102
Tax and Spend	0.0 32	751 87	569 18	532	250 00	230 56	151 37	800 0	- 4787	-7137	-5319	-1944
More money supply	0.0 084	668 72	519 49	508	200 00	202 62	134 74	800 0	- 5339	-5474	-5847	262
More Sensitive Asset demand	0.0 126	669 77	520 15	513	200 00	202 93	134 95	800 0	- 5332	-5495	-5844	293
More investment	0.0 26	677 77	525 19	102 6	200 00	205 33	136 55	800 0	- 5276	-5655	-6301	533
More Exports	0.0 28	704 05	541 75	528	200 00	213 21	141 81	100 00	- 5092	-4181	-5620	1321
Low MPC	0.0 1	489 85	304 54	510	200 00	148 96	989 7	800 0	3636	-1897	3126	-5104
High MPM	0.0 17	569 28	456 85	517	200 00	172 78	171 78	800 0	- 6035	-9178	-6552	-2722

Macroeconomic Time Series of the UK, 1960-2000

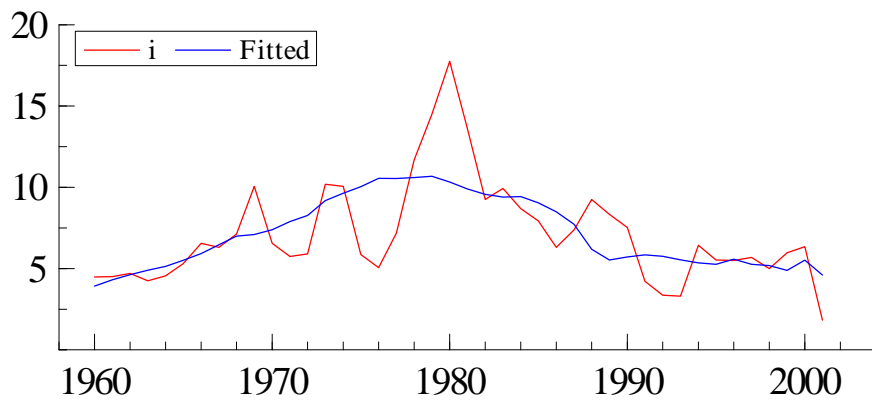
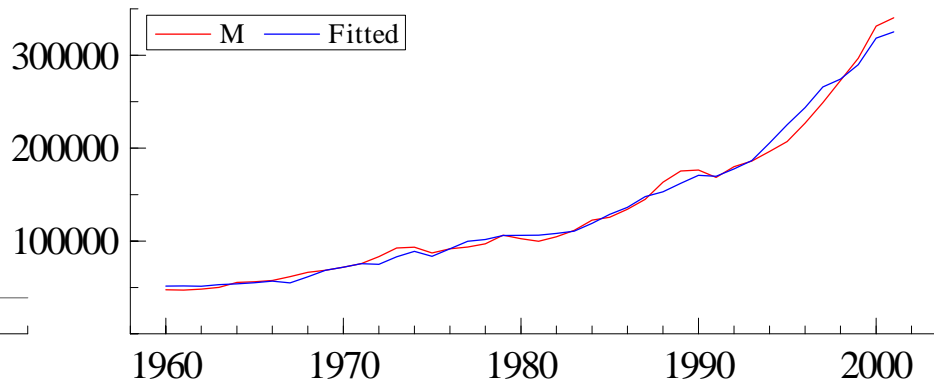
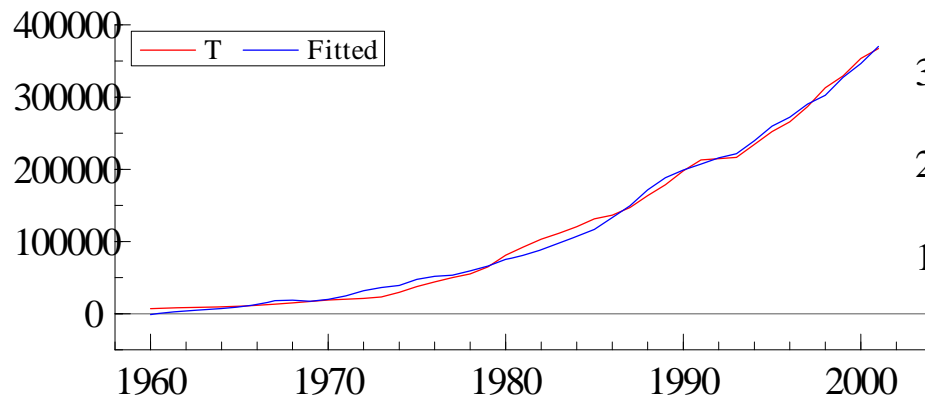
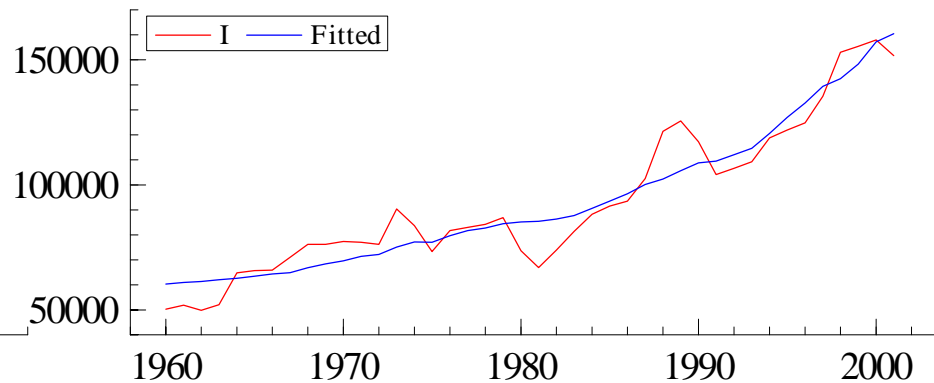
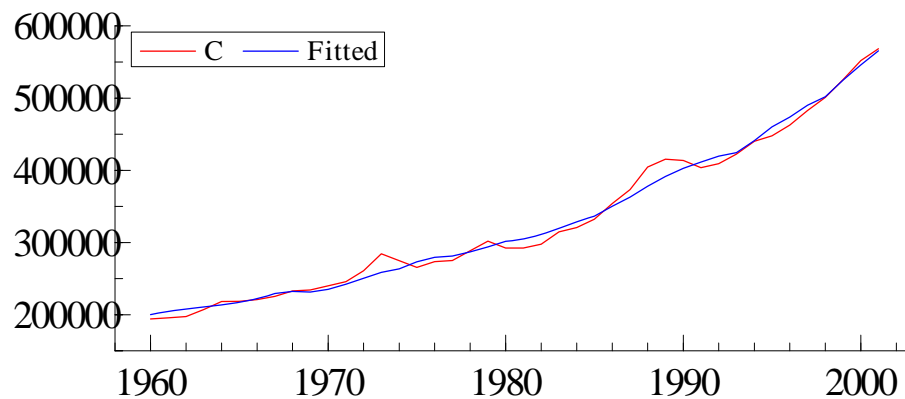


3SLS Estimation of Reduced form of a Keynesian Model

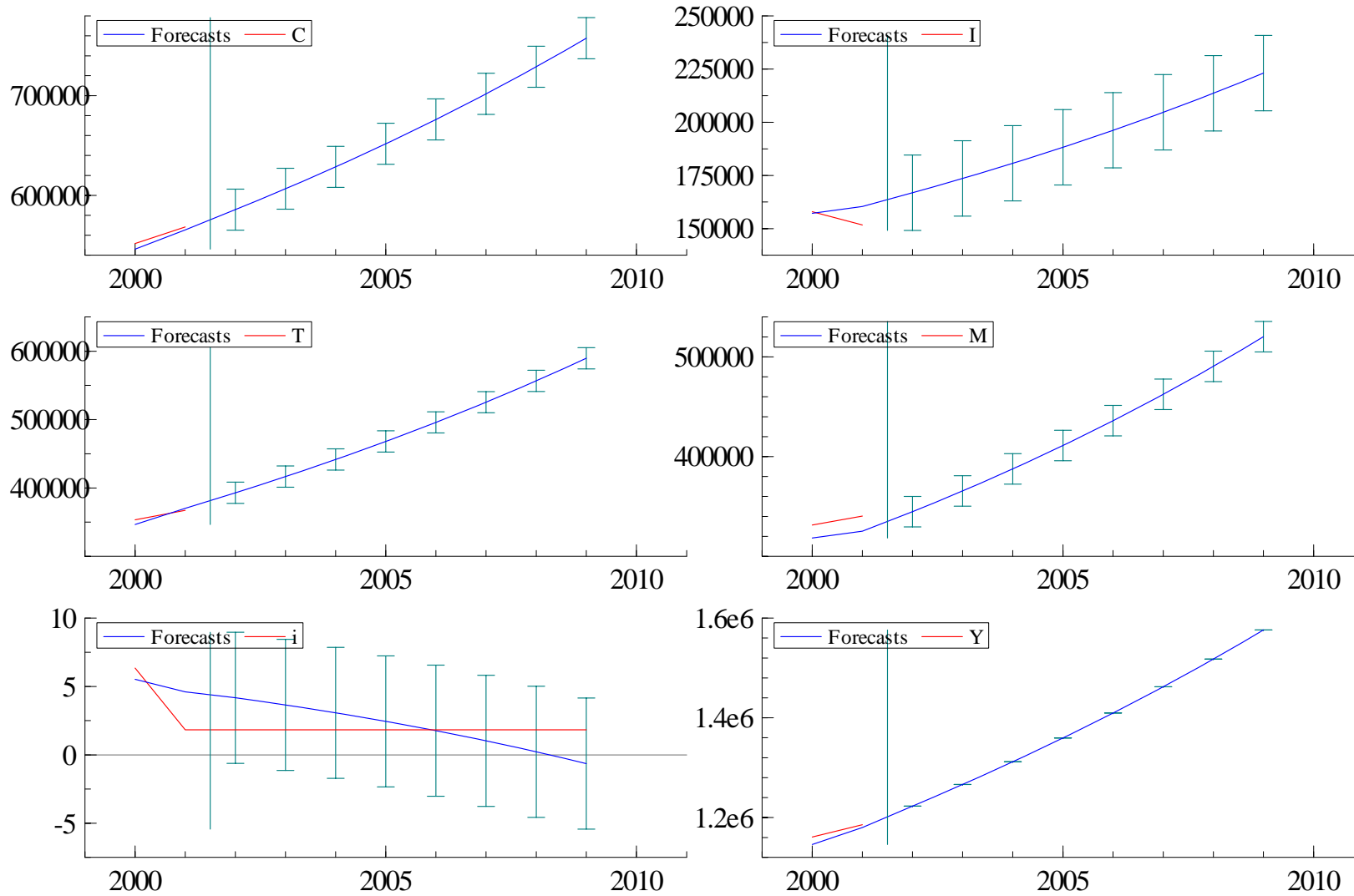
Consumption function	$C = 1.407 * G + 0.1767 * X + 0.2128 * M4 + 8.059e+004$		
	(SE)	(0.212)	(0.154) (0.0266) (1.63e+004)
Investment function:	$I = 0.0684 * G + 0.2681 * X + 0.02907 * M4 + 4.292e+004$		
	(SE)	(0.182)	(0.132) (0.0229) (1.4e+004)
Tax Revenue:	$T = + 0.9521 * G - 0.08909 * X + 0.3204 * M4 - 7.533e+004$		
	(SE)	(0.159)	(0.116) (0.02) (1.23e+004)
Import function:	$M = - 0.4738 * G + 1.003 * X + 0.06508 * M4 + 4.34e+004$		
	(SE)	(0.157)	(0.114) (0.0198) (1.21e+004)
Interest rate:	$i = 0.0001148 * G + 6.273e-005 * X - 2.384e-005 * M4 - 7.408$		
	(SE)	(4.93e-005)	(3.58e-005) (6.2e-006) (3.79)

log-likelihood	-1798.42246	-T/2log Omega	-1500.44537
no. of observations	42	no. of parameters	20

Fit of the Simultaneous Equation Model



Ex-Ante Forecast of the Model Economy



Neo-classical Synthesis of the Keynesian Model: Comparative Static Analysis

$$Y = F(K, N)$$

$$F_N > 0 \quad F_K > 0 \quad F_{NN} < 0 \quad F_{KK} < 0$$

$$W(N) = \int \begin{cases} 0 & \text{for } N \leq \bar{N} \\ + & \text{for } N > \bar{N} \end{cases} \quad W = W_0 + W(N)$$

$$\frac{W}{P} = F_N(N, K)$$

$$C = C(Y^d) \quad Y^d = (1 - \tau)Y$$

$$\frac{M}{P} = M(Y, r) \quad M_y > 0 \quad M_r < 0$$

Reduced form of the Neoclassical synthesis to the Keynesian Model

$$F(N, K) = c(F(N, K) \cdot (1 - \tau)) + I(r) + G + NX$$

$$\frac{W}{P} = F_N(N, K)$$

$$\frac{M}{P} = M(Y, r)$$

$$F_N dN + F_K dK = c(1 - \tau)F_N dN + c(1 - \tau)F_K dK - cd\tau F(N, K) + I_r dr + dG$$

$$\frac{dW}{P} - \frac{W}{P^2} dP = F_{NN} dN + F_{NK} dK$$

$$\frac{dM}{P} - \frac{M}{P^2} dP = M_y F_N dN + M_y F_K dK + M_r dr$$

$$\begin{bmatrix} (1-c(1-\tau))F_N & 0 & -I_r \\ M_y F_N & \frac{M}{P^2} & M_r \\ F_{NN} & \frac{W}{P^2} & 0 \end{bmatrix} \begin{bmatrix} dN \\ dP \\ dr \end{bmatrix} = \begin{bmatrix} c(1-\tau)F_K dK - F_K dK - cd\tau F(N, K) + dG \\ \frac{dM}{P} - M_y F_K dK \\ \frac{dW}{P} - F_{NK} dK \end{bmatrix}$$

$$\Delta = \begin{vmatrix} (1-c(1-\tau))F_N & 0 & -I_r \\ M_y F_N & \frac{M}{P^2} & M_r \\ F_{NN} & \frac{W}{P^2} & 0 \end{vmatrix} = -M_r \frac{W}{P^2} [(1-c(1-\tau))F_N] - I_r \left(M_y F_N \frac{W}{P^2} - F_{NN} \frac{M}{P^2} \right)$$

$$dN = \frac{1}{\Delta} \begin{bmatrix} c(1-\tau)F_K dK - F_K dK - cd\tau F(N, K) + dG & 0 & -I_r \\ \frac{dM}{P} - M_y F_K dK & \frac{M}{P^2} & M_r \\ \frac{dW}{P} - F_{NK} dK & \frac{W}{P^2} & 0 \end{bmatrix}$$

Employment, output, price and interest Effects in the Keynesian Model

$$dN = \frac{1}{\Delta} \left[-I_r \frac{W}{P^2} \left(\frac{dM}{P} - M_y F_K dK \right) + I_r \left(\frac{dW}{P} - F_{NK} dK \right) \frac{M}{P^2} - M_r \frac{W}{P^2} (c(1-\tau)F_K dK - F_K dK - cd\tau F(N, K) + dG) \right]$$

$$dy = \frac{F_N}{\Delta} \left[-I_r \frac{W}{P^2} \left(\frac{dM}{P} - M_y F_K dK \right) + I_r \left(\frac{dW}{P} - F_{NK} dK \right) \frac{M}{P^2} - M_r \frac{W}{P^2} (c(1-\tau)F_K dK - F_K dK - cd\tau F(N, K) + dG) \right]$$

$$\frac{dy}{d\tau} = -cF(N, K) \left(-M_r \frac{W}{P^2} \right)$$

$$dp = \frac{1}{\Delta} \begin{bmatrix} (1-c(1-\tau))F_N & c(1-\tau)F_K dK - F_K dK - cd\tau F(N, K) + dG & -I_r \\ M_y F_N & \frac{dM}{P} - M_y F_K dK & M_r \\ F_{NN} & \frac{dW}{P} - F_{NK} dK & 0 \end{bmatrix}$$

$$dr = \frac{1}{\Delta} \begin{bmatrix} (1-c(1-\tau))F_N & 0 & c(1-\tau)F_K dK - F_K dK - cd\tau F(N, K) + dG \\ M_y F_N & \frac{M}{P^2} & \frac{dM}{P} - M_y F_K dK \\ F_{NN} & \frac{W}{P^2} & \frac{dW}{P} - F_{NK} dK \end{bmatrix}$$

Phillips Curve: Short -Run Dynamics:
Unemployment Inflation Trade-off; policy menu

$$\pi_t = \bar{\pi} + \left\{ \begin{array}{c} a(y - \bar{y}) \\ or \\ -b(u - \bar{u}) \end{array} \right\} + s$$

$$W_t = (1 + \gamma)P_t^e$$

$$P_t = (1 + \theta)(1 + \gamma)P_t^e \quad (1 + \pi_t) = \frac{P_t}{P_{t-1}}$$

$$(1 + \pi_t) = (1 + \theta)(1 + \gamma)(1 + \pi_t^e) \quad \pi_t = \pi_t^e + \theta + \gamma$$

$$\theta + \gamma = a(y_t - \bar{y}) = -b(u_t - \bar{u})$$

Noeclassical model for the long run

Preference:
$$\int_0^{\infty} e^{-\rho t} \frac{C_t^{1-\sigma}}{1-\sigma} dt$$

Technology:
$$Y_t = A_t K_t^\alpha N_t^{1-\alpha} \quad \text{assume } A_t = 1 \quad N_t = 1$$

Capital accumulation:
$$\dot{K}_t = Y_t - N_t C_t - \delta K_t$$

Current value Hamiltonian of this problem

$$H(c, K, \theta) = \frac{C_t^{1-\sigma}}{1-\sigma} + \theta [K_t^\alpha - C_t - \delta K_{t-1}]$$

C is control, K is state variable, θ is co-state variable.

Optimality and Boundary Conditions

First order conditions

$$\frac{\partial H}{\partial C_t} = 0 \rightarrow C_t^{-\sigma} = \theta_t \quad (2)$$

$$\dot{\theta}_t = \rho\theta_t - \frac{\partial H_t}{\partial K_t} \rightarrow \dot{\theta}_t = \rho\theta_t - \theta_t \left[\alpha K_t^{\alpha-1} - \delta \right] \quad (3)$$

$$\dot{K}_t = K_t^\alpha - N_t C_t - \delta K_t \quad (4)$$

Transversality condition

$$\lim_{n \rightarrow \infty} e^{-\rho t} \theta_t K_t = 0 \quad (5)$$

Characterisation of the Balanced Growth Path

Capital stock, consumption and the shadow price of capital remain constant in the

balanced growth path $\frac{\dot{C}}{C} = g_c$; $\frac{\dot{K}}{K} = g_K$ and $\frac{\dot{\theta}_t}{\theta_t} = g_\theta$. From (3)

$$\frac{\dot{\theta}_t}{\theta_t} = \rho - [\alpha K_t^{\alpha-1} - \delta] \rightarrow \alpha K_t^{\alpha-1} = \rho - \frac{\dot{\theta}_t}{\theta_t} + \delta \quad (6)$$

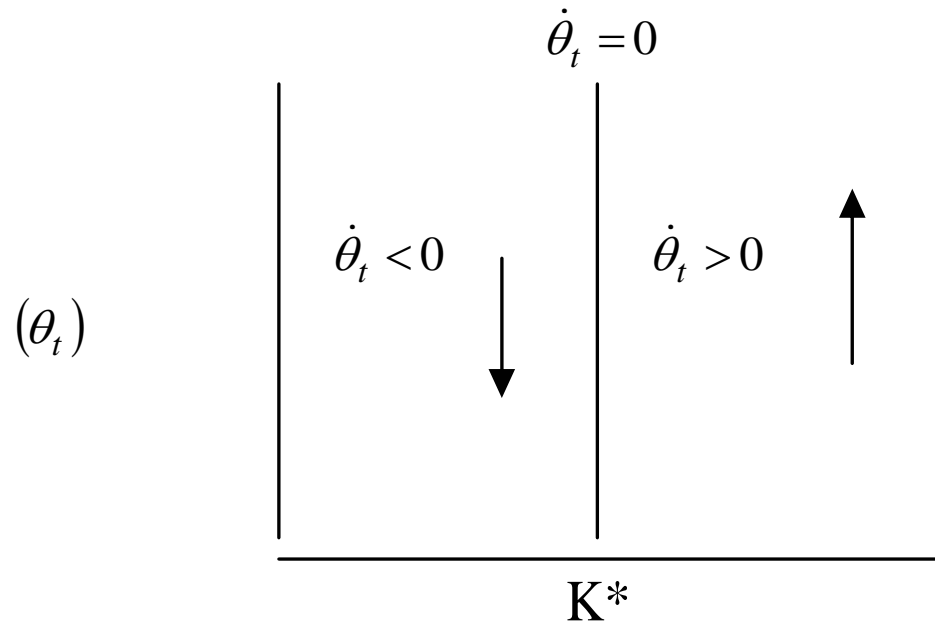
Since the RHS is constant, therefore LHS also should be constant $\frac{\dot{K}}{K} = 0$. If capital stock

is not growing output is not growing $\frac{\dot{Y}}{Y} = 0$ and consumption is not growing $\frac{\dot{C}}{C} = 0$.

$$\text{From (2)} \quad \frac{\dot{\theta}_t}{\theta_t} = -\sigma \frac{\dot{C}_t}{C_t} \rightarrow \frac{\dot{\theta}_t}{\theta_t} = 0 \quad (7)$$

Transitional Dynamics-1

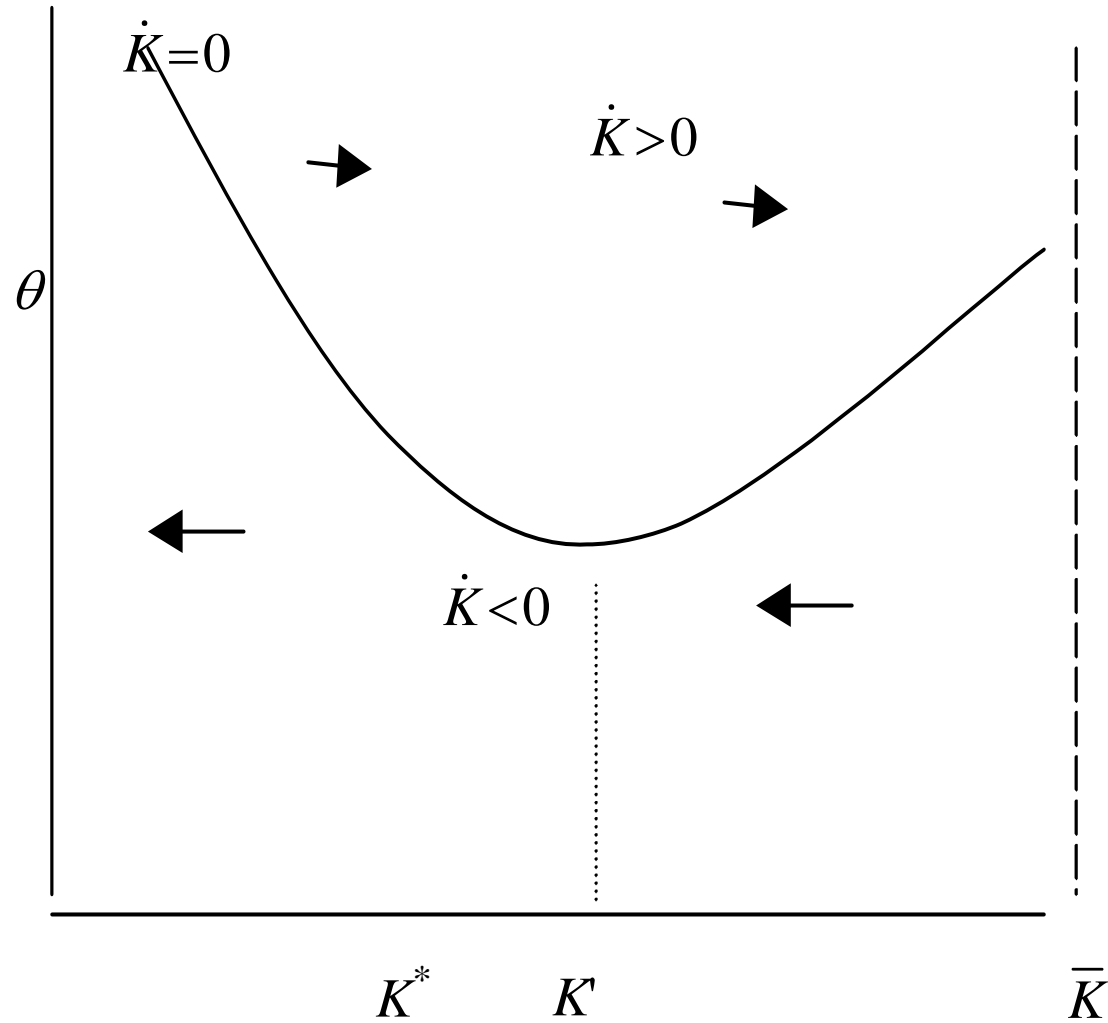
In (θ_t, K_t) space the transition dynamics of the shadowprice θ_t relative to the steady state capital stock is that



$$K^* = \left[\frac{\alpha}{\rho + \delta - \frac{\dot{\theta}}{\theta}} \right]^{\frac{1}{1-\alpha}}$$

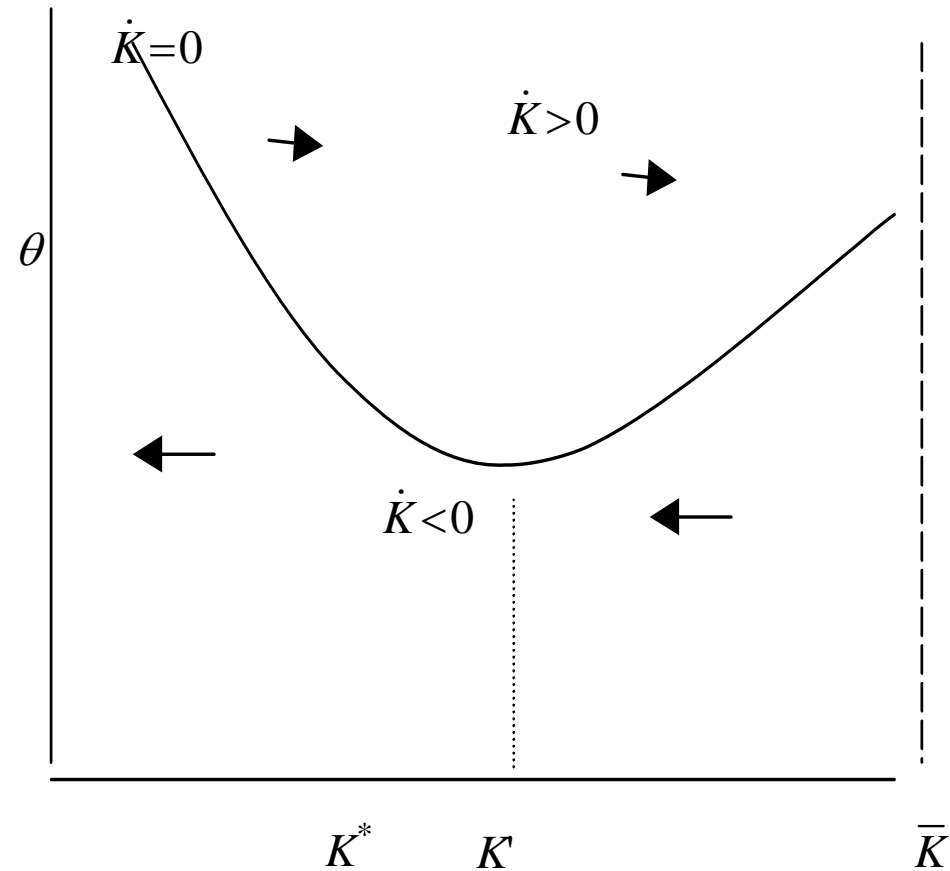
Transitional Dynamics-2

$$\bar{K} > K^* > K.$$



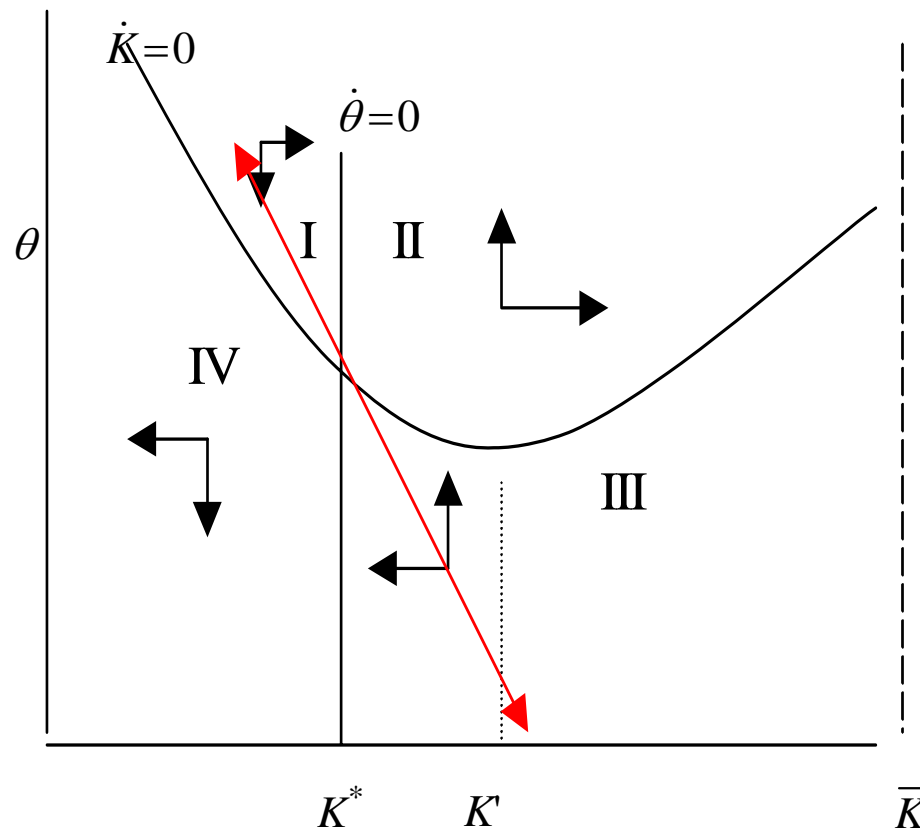
Transitional Dynamics-2

$$\bar{K} > K^* > K.$$



Saddle Point Solution

Putting all these things together the convergence to the steady state can be summarised in the following diagram.



Convergence to the steady state lies in region I and III as shown by the double arrow red line.